## Lezione 6

Bioinformatica

## Mauro Ceccanti ${ }^{\ddagger}$ e Alberto Paoluzzi ${ }^{\dagger}$

†Dip．Informatica e Automazione－Università＂Roma Tre＂ $\ddagger$ Dip．Medicina Clinica－Università＂La Sapienza＂

Lab 01：Numerical Python
Installing NumPy
Numerical Python Quick Tour

## The Basics

NumPy for Matlab Users
Introduction to geometric module Pytrsxge

## Contents

Lab 01：Numerical Python
Installing NumPy
Numerical Python
Quick Tour
The Basics
NumPy for Matlab Users
Introduction to geometric module Pytrsxge

## Installing NumPy

As with a lot of open－source software，the best way to fully exploit and contribute to Scipy is to compile it from source．This will guarantee you the latest stable releases and a better support from mailing－lists．However，this can be challenging，and the second best way to run Scipy is to use binaries

## Binaries for Windows and MacOSX available ！

NumPy：choose version 1．3．0
Official releases are on SourceForge download site for numpy

## SciPy：choose version 0．7．1

Official releases are on SourceForge download site for scipy

## Contents

Lab 01: Numerical Python
Installing NumPy

```
Numerical Python
    Quick Tour
    The Basics
    NumPy for Matlab Users
    Introduction to geometric module Pytrsxge
```


## Quick Tour

- NumPy is a Python library for working with multidimensional arrays
- The main data type is an array
- An array is a set of elements, all of the same type, indexed by a vector of nonnegative integers.


## Best way to learn

Browse within the Numpy Example List, with added documentation from doc strings and arguments specification for methods and functions of Numpy

## Numpy Example List With Doc

## EXAMPLE:

numpy.sin()

## ALSO:

Tentative NumPy Tutorial

## Quick Tour

Arrays can be created in different ways:

```
>>> from numpy import *
>>> a = array( [ 10, 20, 30, 40 ] )
# create an array out of a list
>>> a
array([10, 20, 30, 40])
>>> b = arange( 4 )
# create an array of 4 integers, from 0 to 3
>>> b
array([0, 1, 2, 3])
>>> c = linspace(-pi,pi,3)
# create an array of 3 evenly spaced samples from -pi to
    pi
>>> c
array([-3.14159265, 0. , 3.14159265])
```


## Quick Tour

New arrays can be obtained by operating with existing arrays:

```
>>> d = a+b**2 # elementwise operations
3 >>> d
array([10, 21, 34, 49])
```

2

## Quick Tour

and you can change the dimensions of existing arrays:

```
>>> y = arange(12)
>>> y
array([ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11])
>>> y.shape = 3,4
# does not modify the total number of elements
>>> y
array([[ 0, 1, 2, 3],
    [4, 5, 6, 7]
    [ 8, 9, 10, 11]])
```

REMARK: The evaluation of a statement does not produce an output, whereas the evaluation of an expression returns its value

## Quick Tour

Arrays may have more than one dimension:

```
>>> x = ones( (3,4) )
>>> x
array([[1., 1., 1., 1.],
    [1., 1., 1., 1.],
    [1., 1., 1., 1.]])
>>> x.shape # a tuple with the dimensions
(3, 4)
>>> y = zeros( (3,4)
>>> y
array([[ 0., 0., 0., 0.],
    [ 0., 0., 0., 0.],
    [ 0., 0.,
```


## EXERCISE: generate the $n \times n$ identity matrix in 3 different ways

## Quick Tour

It is possible to operate with arrays of different dimensions as long as they fit well (broadcasting):

```
>>> 3*a # multiply each element of a by 3
array([ 30, 60, 90, 120])
>>> a+y # sum a to each row of y
array([[10, 21, 32, 43]
    [14, 25, 36, 47],
    [18, 29, 40, 51]])
```


## Quick Tour

Similar to Python lists, arrays can be indexed, sliced and iterated over

```
>>> a[2:4] = -7,-3
# modify last two elements of a
>>> for i in a: # iterate over a
... print i
10
20
-7
-3
```


## Quick Tour

Arrays can be created in different ways:

```
>>> from numpy import *
>>> a = array( [ 10, 20, 30, 40 ] )
# create an array out of a list
>>> a
array([10, 20, 30, 40])
>>> b = arange( 4 )
# create an array of 4 integers, from 0 to 3
>>> b
array([0, 1, 2, 3])
>>> c = linspace(-pi,pi,3)
# create an array of 3 evenly spaced samples from - }\pi\mathrm{ to }
>>> c
array([-3.14159265, 0. , 3.14159265])
```


## Quick Tour

When indexing more than one dimension, indices are separated by commas:

```
>>> x[1,2] = 20
>>> x[1,:]
    # x's second row
array([ 1, 1, 20, 1])
>> x[0] = a
    # change first row of x
>>> x
array([[10, 20, -7, -3],
    [ 1, 1, 20, 1],
    [ 1, 1, 1, 1]])
```

REMARK: Indexing and slicing allow access to array elements both in reading and in writing mode

## Contents

## Lab 01: Numerical Python

Installing NumPy
Numerical Python
Quick Tour

## The Basics

NumPy for Matlab Users
Introduction to geometric module Pytrsxge

The multidimensional array class is called ndarray
Note that this is not the same as the Standard Python Library class array, which is only for one-dimensional arrays

The more important attributes of an ndarray object are:
ndarray.ndim the number of axes (dimensions) of the array. In the Python world, the number of dimensions is often referred to as rank.
ndarray.shape the dimensions of the array. This is a tuple of integers indicating the size of the array in each dimension. For a matrix with $n$ rows and $m$ columns, shape will be ( $n, m$ ). The length of the shape tuple is therefore the rank, or number of dimensions, ndim.
ndarray.size the total number of elements of the array. This is equal to the product of the elements of shape.

## An example

We define the following array.

```
>>> a = arange(10).reshape (2,5)
>>> a
array([[0, 1, 2, 3, 4],
[5, 6, 7, 8, 9]])
```

We have just created an array object with a label a attached to it. The array a has several attributes -or properties. In Python, attributes of a specific object are denoted name_object.attribute. In our case:

- a.shape is $(2,5)$
- a.ndim is 2 (which is the length of a. shape)
- a.size is 10
- a.dtype. name is int 32
- a.itemsize is 4 , which means that an int 32 takes 4 bytes in memory.
> ndarray.dtype an object describing the type of the elements in the array. One can create or specify dtype's using standard Python types. NumPy provides a bunch of them, for example: bool character, int, int8, int16, int32, int64, float, float8, float16, float32, float64, complex_, complex64, object_.
> ndarray.itemsize the size in bytes of each element of the array. For example, an array of elements of type float64 has itemsize $8(=64 / 8)$, while one of type complex32 has itemsize $4(=32 / 8)$. It is equivalent to ndarray.dtype.itemsize.
> ndarray.data the buffer containing the actual elements of the array. Normally, we won't need to use this attribute because we will access to the elements in an array using indexing facilities.


## Python Short Course

Lecture2: Numerical Python

Download the "Lecture2: Numerical Python", by Richard P. Muller at Caltech

## EXERCISE

Try to execute several simple examples (written in May, 2000) and adapt them to current version of Numpy

## Contents

Lab 01: Numerical Python
Installing NumPy
Numerical Python
Quick Tour
The Basics

## NumPy for Matlab Users

Introduction to geometric module Pytrsxge

## Contents

Lab 01: Numerical Python
Installing NumPy
Numerical Python
Quick Tour
The Basics
NumPy for Matlab Users
Introduction to geometric module Pytrsxge

## NumPy for Matlab Users

Look carefully at the first sections of the linked web page

## NumPy for Matlab Users

Pytrsxge: geometric kernel of Plasm language
HPC (hierarchical polyhedral complex) is the name of the geometric type

```
1 from math import *
from pytrsxge import *
4 # mkpol (MaKe POLyhedron) in 2D
5 Plasm.View(Plasm.mkpol(2,[0,0, 1,0 ,1,1, 0,1],
    [[0,1,2],[2,0,3]] ))
7 # mkpol in 3D
8 Plasm.View(Plasm.mkpol(3,[0,0,0,1,0,0,1,1,0,0,1,0,
    0,0,1,1,0,1,1,1,1,0,1,1],[[0,1,2,3,4,5,6,7]]))
9
10 # example of structure
11 args = [Plasm.cube(0), Plasm.translate(Plasm.cube(1),
    3,1,1), Plasm.translate(Plasm.cube(2),3,1,2), Plasm.
    translate (Plasm.cube (3), 3,1,3)]
12 Plasm.View(Plasm.Struct (args))
```


## Introduction to Pytrsxge package

It is the Python porting of the geometric kernel xge of the Plasm Language
11

```
# apply a transformation matrix (homogeneous components
```


# apply a transformation matrix (homogeneous components

    in first row/col)
    in first row/col)
    vmat=Matf([1,0,0,0, 0,1,0,1, 0,0,1,1,0,0,0,1])
vmat=Matf([1,0,0,0, 0,1,0,1, 0,0,1,1,0,0,0,1])
Plasm.View(Plasm.transform(Plasm.cube(3),vmat,vmat.
Plasm.View(Plasm.transform(Plasm.cube(3),vmat,vmat.
invert()))
invert()))

# scale an hpc

# scale an hpc

Plasm.View(Plasm.scale(Plasm.cube (3),Vecf(0.0,
Plasm.View(Plasm.scale(Plasm.cube (3),Vecf(0.0,
1.0,2.0,3.0)))
1.0,2.0,3.0)))

# translate an hpc

# translate an hpc

Plasm.View(Plasm.translate(Plasm.cube (3),Vecf(0.0,
Plasm.View(Plasm.translate(Plasm.cube (3),Vecf(0.0,
1.0,2.0,3.0)))
1.0,2.0,3.0)))
12 Plasm.View(Plasm.Struct([Plasm.cube(3), Plasm.rotate(
12 Plasm.View(Plasm.Struct([Plasm.cube(3), Plasm.rotate(
Plasm.cube(3), 3,1,2,pi)]))

# rotate an hpc

```
# rotate an hpc
```

Graph of the $\sin ()$ function
REMARK: every graphics object is a linear approximation of the smooth shape

from numpy import *
from pytrsxge import *
Plasm.View(polyline(points))

The pytrsxge package is the Python porting of the Plasm language

## Graph of the $\sin ()$ function

from numpy import *
from pytrsxge import *
c = linspace(-pi,pi,16)
points=array (zip(c,sin(c))) 5
def polyline (points): n,d = points.shape points.shape $=n * d$ return Plasm.mkpol(d, 10 points, zip (range (n 11 -1), range (1,n))) 12

Plasm.View(polyline (points) 44 15
16
17
18 19

```
>>> print points
[[ -3.14159265e+00 -1.22464680e-16]
[ -2.72271363e+00 -4.06736643e-01]
[ -2.30383461e+00 -7.43144825e-01]
[ -1.88495559e+00 -9.51056516e-01]
[ -1.46607657e+00 -9.94521895e-01]
[ -1.04719755e+00 -8.66025404e-01]
[ -6.28318531e-01 -5.87785252e-01]
[ -2.09439510e-01 -2.07911691e-01]
[ 2.09439510e-01 2.07911691e-01]
[ 6.28318531e-01 5.87785252e-01]
[ 1.04719755e+00 8.66025404e-01]
9.94521895e-01]
[ 1.88495559e+00 9.51056516e-01]
    7.43144825e-01]
    4.06736643e-01]
    1.22464680e-16]
3.14159265e+00
>>> points.size
32
```


## Pentose and aromatic shape

REMARK: every graphics object is a linear approximation of the smooth shape


In organic chemistry, the structures of some rings of atoms are unexpectedly stable. Aromaticity is a chemical property in which a conjugated ring of unsaturated bonds, lone pairs, or empty orbitals exhibit a stabilization stronger than would be expected by the stabilization of conjugation alone. It can also be considered a manifestation of cyclic delocalization and of resonance. This is usually considered to be because electrons are free to cycle around circular arrangements of atoms, which are alternately single-and double-bonded to one another.
commonly-seen model of aromatic rings, ningle bond and a double bond, each bond in the ring identical to every other. This single and double bonds (cyclohexatriene), was developed by Kekulé (see History section below). The model for benzene consists of two resonance forms, which corresponds to the double and single bonds' switching positions. Benzene is a more stable molecule than would be expected without accounting for charge delocalization.

## Graph of the sin() function

REMARK: every graphics object is a linear approximation of the smooth shape ..

```
from numpy import *
from pytrsxge import *
# circle
c = linspace(-pi,pi,6)
p = array( zip(cos(c), sin(c)) )
Plasm.View(polyline(p))
# pentagon with legs
a3 = map(polyline, map(array, zip(p, 1.5*p)) )
Plasm.View(Plasm.Struct( a3 + [polyline(p)] ))
# hexagon with legs
c = linspace(-pi,pi,7)
p = array( zip(cos(c), sin(c)) )
a3 = map(polyline, map(array, zip(p, 1.5*p)) )
q = Plasm.Struct( a3 + [polyline(p)] )
Plasm.View(q)
```


## Parametric helix curve

The 'pitch' is the (constant) distance between (any) pair of closest points

from numpy import *
from pytrsxge import *
def helixpoints(radius, pitch, nturns):
$c=$ linspace ( $0,2 * p i \star n t u r n s, 12 *$ nturns $)$
return array(zip( cos(c),sin(c), c*(pitch /(2*pi)) ) )
def helix(radius, pitch, nturns):
return polyline(helixPoints(radius,pitch, nturns))

```
Plasm.View(helix (1, 1.5,6))
```

DNA structure
The ukpol function returns the vertices of its hpc argument

def dnaStructure(radius, pitch, nturns):
p = helixPoints(radius,pitch, nturns)
q = array (matrix(p) * matrix([ [-1,0,0], $[0,-1,0],[0,0,1]])$ )
diameters = map(polyline, map(array, zip(p. tolist(), q.tolist())) )
return Plasm.Struct( diameters + [polyline(p ),polyline(q)] )

Plasm.View (dnaStructure (1, 2, 4))

## Deoxyribonucleic acid (DNA) fragment

Gene: The basic biological unit of heredity. A segment of DNA needed to contribute to a function.

left image: 10 K base pairs other images: subset enlargement

## 3D polylines

The backbone of the 2 J 5 Y protein


