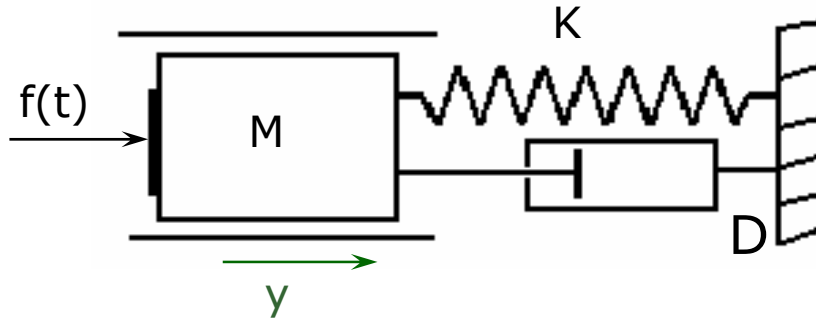

ESEMPI

SISTEMA MASSA MOLLA SMORZATORE
POSIZIONE DEL CARRELLINO

SIST. MASSA-MOLLA-SMORZATORE



$$\begin{aligned}M &= 1 \\D &= 2 \\K &= 101\end{aligned}$$

$$f(t) = \delta_{-1}(t), \quad \underbrace{y(0) = 0, \quad \dot{y}(0) = 0}_{\text{Sist. a riposo}}$$

Ovvero:
le sospensioni

$$\begin{aligned}M\ddot{y}(t) + D\dot{y}(t) + Ky(t) &= f(t) \\Ms^2Y(s) + DsY(s) + KY(s) &= F(s)\end{aligned}$$

Analogo del
sistema R-L-C

$$Y(s) = \frac{1}{Ms^2 + Ds + K} F(s) = \frac{1}{s^2 + 2s + 101} \cdot \frac{1}{s} = \frac{N}{D}$$

$$Y(s) = \frac{1}{Ms^2 + Fs + K} F(s) = \frac{1}{s^2 + 2s + 101} \cdot \frac{1}{s} = \frac{N}{D}$$

$$p_1 = 0 \quad p_2 = -1 - 10j; \quad p_3 = p_2^*$$

$$R_1 = \lim_{s \rightarrow 0} s \frac{N}{D} = \frac{1}{101} \rightarrow \frac{1}{101} \delta_{-1}(t)$$

$$R_2 = \lim_{s \rightarrow -1-10j} (s + 1 + 10j) \cdot \frac{N}{D} = -\frac{1}{202} - \frac{j}{2020}$$

$$R_3 = R_2^* ;$$

$$\frac{R_2}{s + 1 + 10j} + \frac{R_3}{s + 1 - 10j} = -\frac{s + 2}{101(s^2 + 2s + 101)}$$

Dobbiamo antitrasformare $-\frac{s+2}{101(s^2+2s+101)}$

I poli sono cplx, quindi usiamo

$$e^{-\sigma t} \sin(\omega t) \rightarrow \frac{\omega}{(s+\sigma)^2 + \omega^2} = \frac{\omega}{s^2 + 2\sigma s + (\sigma^2 + \omega^2)}$$

$$e^{-\sigma t} \cos(\omega t) \rightarrow \frac{s+\sigma}{s^2 + 2\sigma s + (\sigma^2 + \omega^2)}$$

Da cui: $\sigma = 1$, $\omega = 10$ e possiamo risolvere:

$$A(s+\sigma) + B\omega = -(s+2) \quad A = -1; \quad B = -0.1$$

E quindi la antitrasformata è

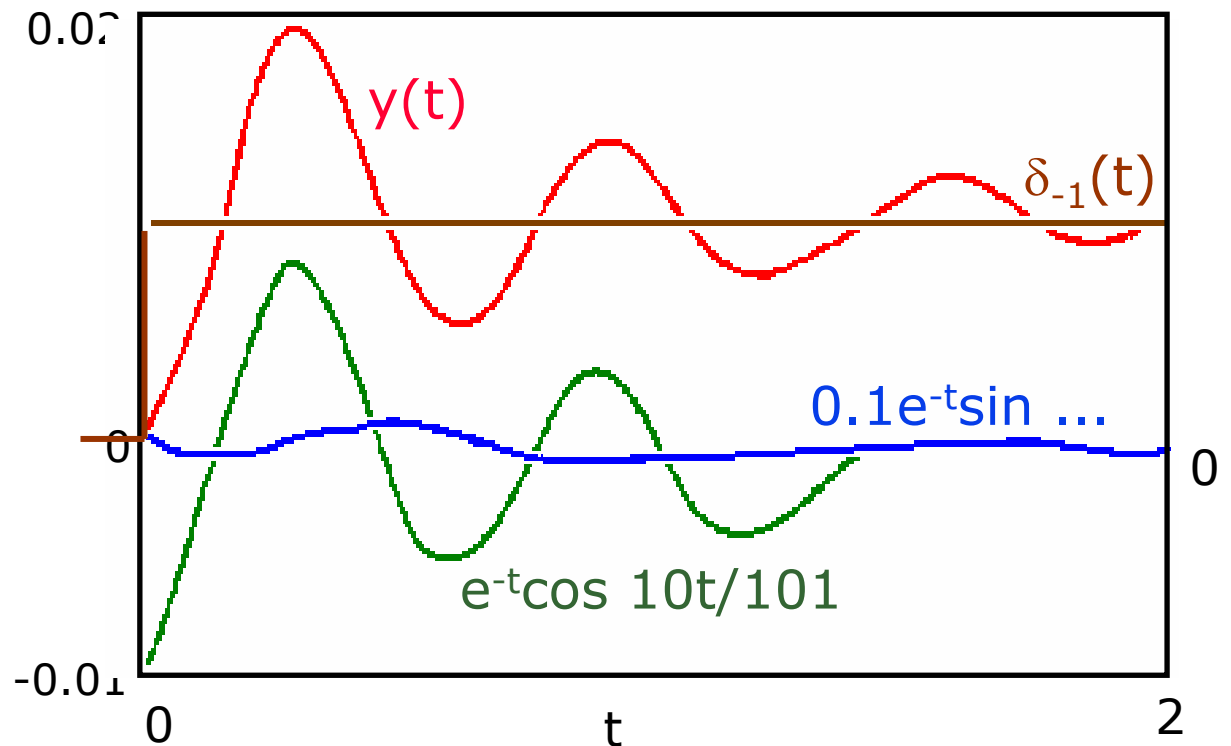
$$\left(-e^{-t} \cos 10t - \frac{e^{-t}}{10} \sin 10t \right)$$

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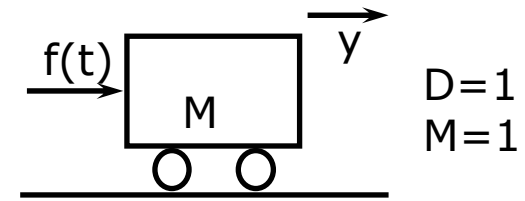
$$y(t) = \frac{1}{101} \left[\delta_{-1}(t) - \underbrace{\left(e^{-t} \cos 10t - \frac{e^{-t}}{10} \sin 10t \right)}_{\text{transitorio legato all'ingresso}} \right]$$

simile all'ingresso

transitorio
legato all'ingresso



$$M\ddot{y} + D\dot{y} = f(t) \quad y(0) = 0, \dot{y}(0) = 0$$



$$f_a = D\dot{x}$$

$$Y(s)[Ms^2 + Fs] = F(s); \quad f(t) = \delta_{-1}(t)$$

$$Y(s) = \frac{1}{s(Ms + D)} \cdot \frac{1}{s} = \frac{1}{s^2(Ms + D)} =$$

$$= \frac{R_1^{(1)}}{s} + \frac{R_1^{(2)}}{s^2} + \frac{R_2}{s+1}$$

doppio polo
nell'origine

Calcolo dei residui

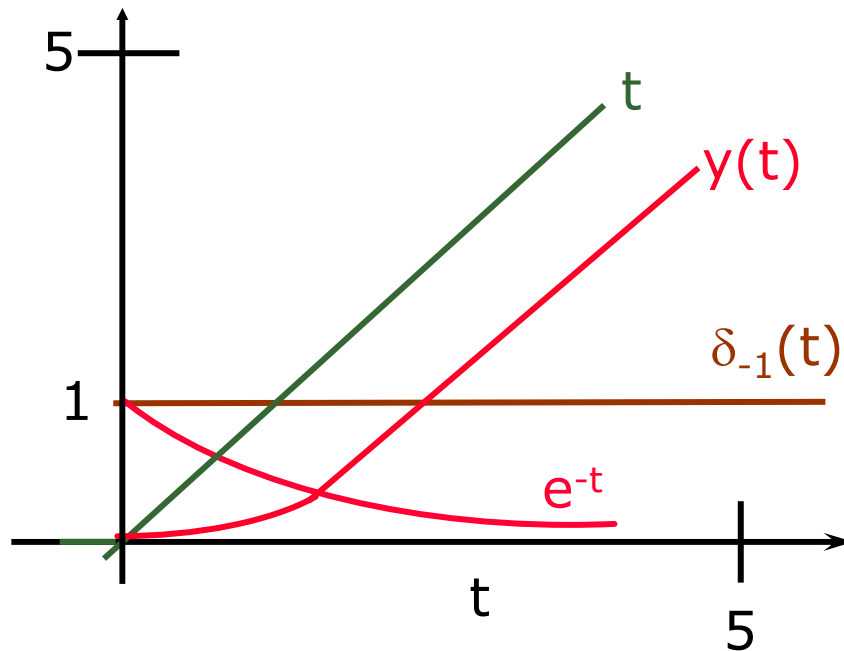
$$R_1^{(2)} = \lim_{s \rightarrow 0} s^2 \frac{1}{s^2(s+1)} = 1$$

$$R_2 = \lim_{s \rightarrow -1} (s+1) \frac{1}{s^2(s+1)} = 1$$

$$R_1^{(1)} = \lim_{s \rightarrow 0} \frac{d}{ds} \left[s^2 \frac{1}{(s+1)s^2} \right] = \lim_{s \rightarrow 0} -\frac{1}{(s+1)^2} = -1$$

$$Y(s) = -\frac{1}{s} + \frac{1}{s^2} + \frac{1}{s+1}$$

$$y(t) = +\delta_{-1}(t) \left[-1 + t + e^{-t} \right]$$



Qual'è la parte simile all'ingresso?

Il sistema non è asintoticamente stabile quindi il transitorio non si annulla!