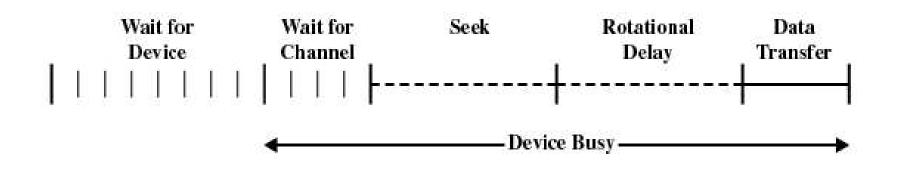
#### disk scheduling

1

#### Disk Performance Parameters

- To read or write, the disk head must be positioned at the desired track and at the beginning of the desired sector
- Seek time
  - Time it takes to position the head at the desired track
- Rotational delay or rotational latency
  - Time it takes for the beginning of the sector to reach the head

#### Timing of a Disk I/O Transfer



#### Figure 11.6 Timing of a Disk I/O Transfer

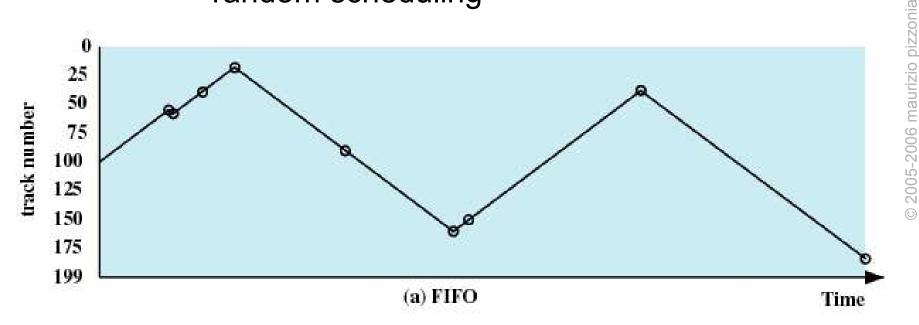
#### Disk Performance Parameters

- Access time
  - Sum of seek time and rotational delay
  - The time it takes to get in position to read or write
- Data transfer occurs as the sector moves under the head

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- Seek time is the reason for differences in performance
- For a single disk there will be a number of I/O requests
- If requests are selected randomly, we will poor performance

- First-in, first-out (FIFO)
  - Process request sequentially
  - Fair to all processes
  - if there are many processes it performs like random scheduling

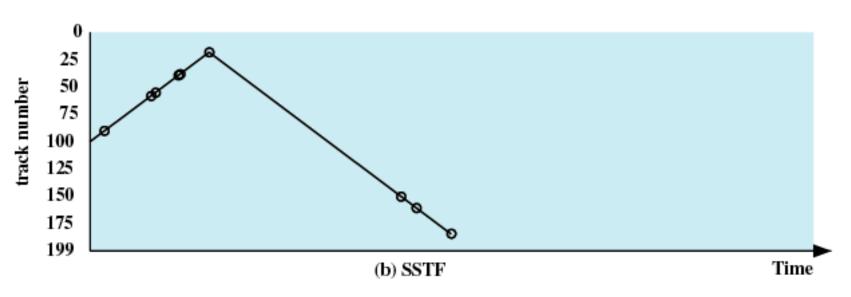


- Priority
  - Goal is not to optimize disk use but to meet other objectives
  - Short batch jobs may have higher priority
  - Provide good interactive response time

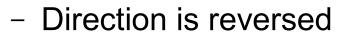
## © 2005-2006 maurizio pizzonia

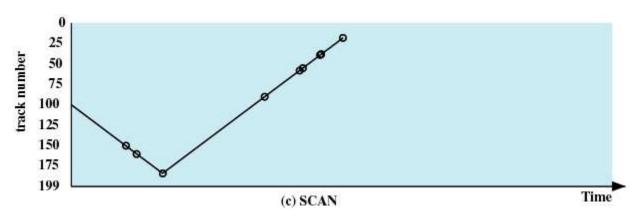
- Last-in, first-out
  - Good for transaction processing systems
    - The device is given to the most recent user so there should be little arm movement
  - Possibility of starvation since a job may never regain the head of the line

- Shortest Service Time First
  - Select the disk I/O request that requires the least movement of the disk arm from its current position
  - Always choose the minimum Seek time
  - Possibility of starvation



- SCAN (LOOK, ELEVATOR)
  - no starvation
  - Arm moves in one direction only, satisfying all outstanding requests until it reaches the last track in that direction





#### RAID

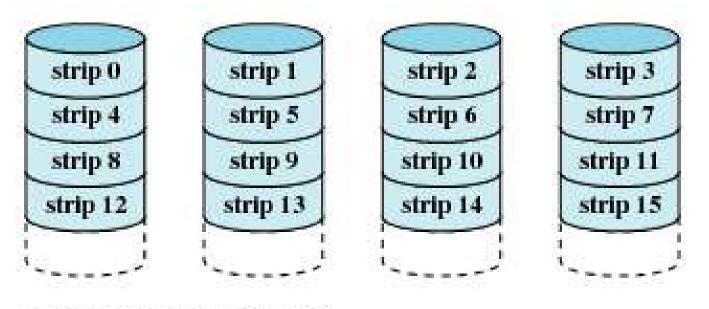
- Redundant Array of Independent Disks
- Set of physical disk drives viewed by the operating system as a single logical drive
- Data are distributed across the physical drives of an array
- Redundant disk capacity is used to store parity information

#### type of requests

- large I/O
  - big files (streaming, bulk)
  - usually of sectors stored contiguously
- High requests rates
  - very high frequency of requests for a very small amount of data
  - usually scattered through the disk

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#### RAID 0 (non-redundant, striping)

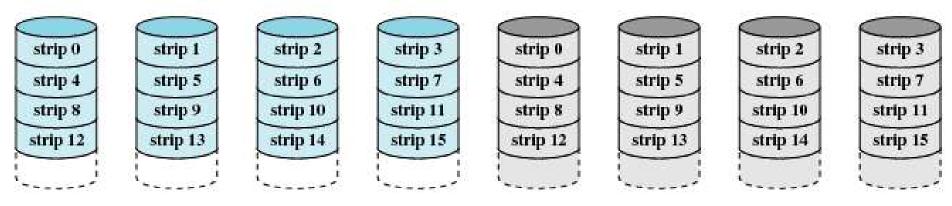


(a) RAID 0 (non-redundant)

- availability: lower than single disk
- large I/O: very good
- high request rate: very good

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#### RAID 1 (mirrored)

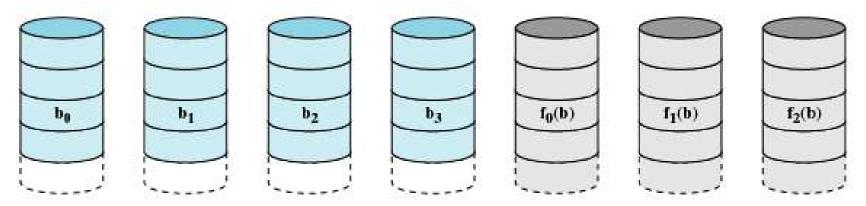


(b) RAID 1 (mirrored)

- availability: high
- large I/O and high request rate: very good for read, like a single disk for write

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## RAID 2 (redundancy through Hamming code)

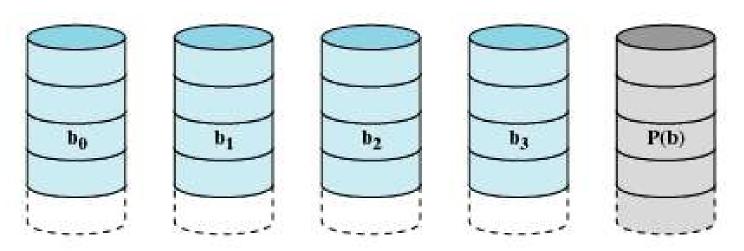


(c) RAID 2 (redundancy through Hamming code)

- disks should be syncronized
- availability: high also for high bit error rate
- large I/O: best!!!
- high request rate: better than a single disk
- expensive!

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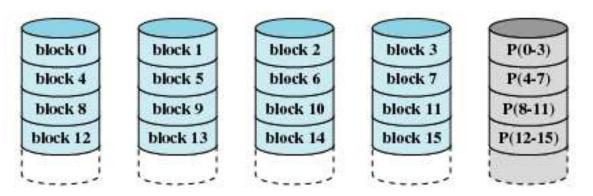
#### RAID 3 (bit-interleaved parity)



(d) RAID 3 (bit-interleaved parity)

- disks should be syncronized
- availability: high
- large I/O: best!!!
- high request rate: better than a single disk

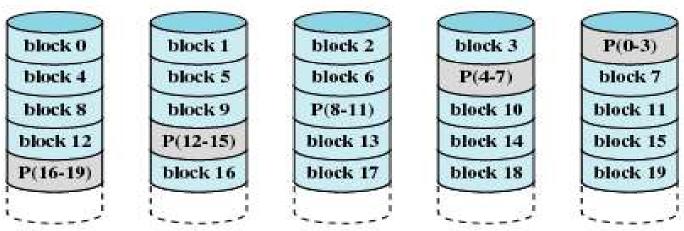
#### RAID 4 (block-level parity)



(e) RAID 4 (block-level parity)

- disks are independent
- availability: high
- P is a bottlenek for write
- large I/O: good, very bad for write
- high request rate: very good for read, very bad for write

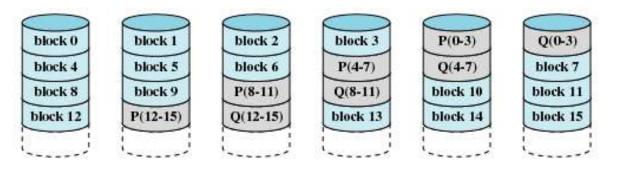
### RAID 5 (block-level distributed parity)



(f) RAID 5 (block-level distributed parity)

- disks are independent
- availability: high
- large I/O: very good, bad for write (no bottlenek)
- high request rate: very good for read, bad for write

#### RAID 6 (dual redundancy)



(g) RAID 6 (dual redundancy)